

Recent PHIL Testing at CAPS

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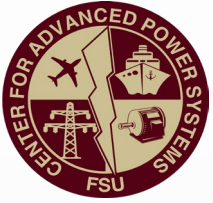


Outline

- CAPS Overview
- PHIL testing of
 - Diesel Generators
 - Energy Magazines
 - Islanded Microgrids



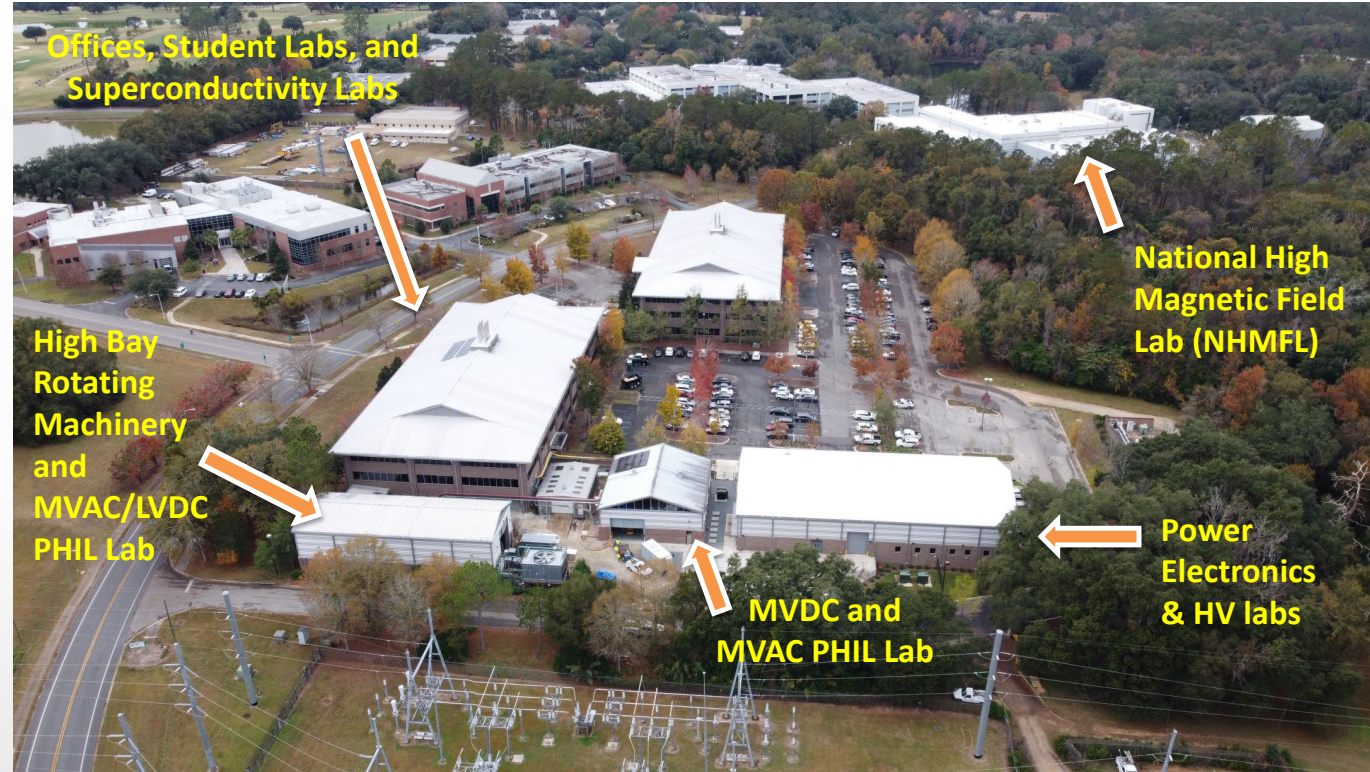
Center for Advanced Power Systems @ FSU



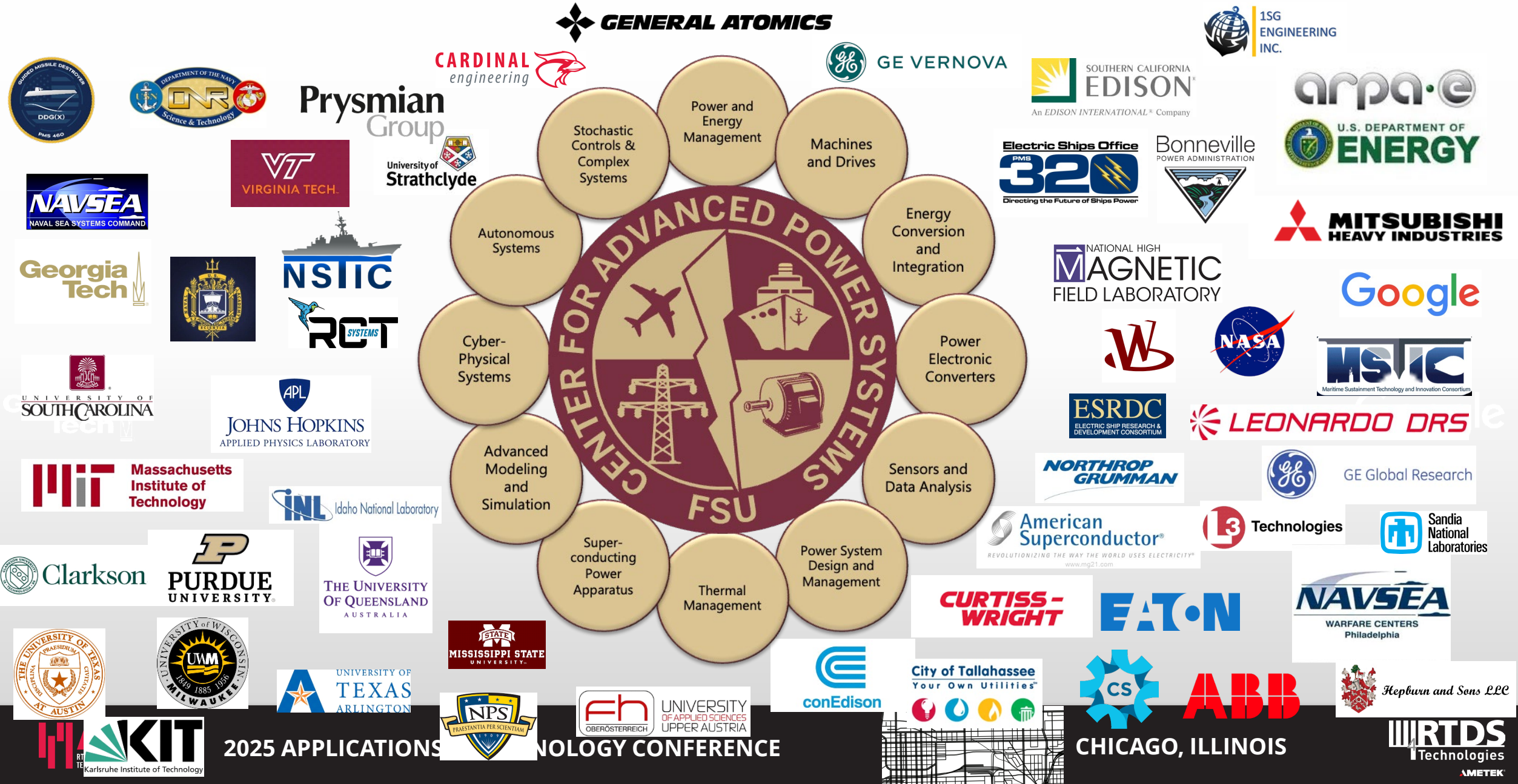
Established in 2000



- Spun off from **NHMFL** in **2000**
- **Research** and **education** related to application of new technologies to electric power systems
- Closely affiliated with **FAMU-FSU College of Engineering**
- 56,000 ft² laboratories/offices; CUI data **security compliant**
- Tenure/Non-tenure track **faculty**, **Ph.D./M.S./B.S. students**, staff **researchers** and **post-doctorial associates** and **facility support**
- Over **\$105 million** specialized **power and energy capabilities** funded by ESO, ONR, DOE, NSF and Industry
- **Manager** of the ONR funded Electric Ship Research and Development Consortium (**ESRDC**)
- Contracted by **PEO Ships PMS460** to derisk the DDG(X) Power System and conduct HIL based demonstrations and DT&E of advanced P&E technologies supportive of multiple ship classes



Clients and Collaborators



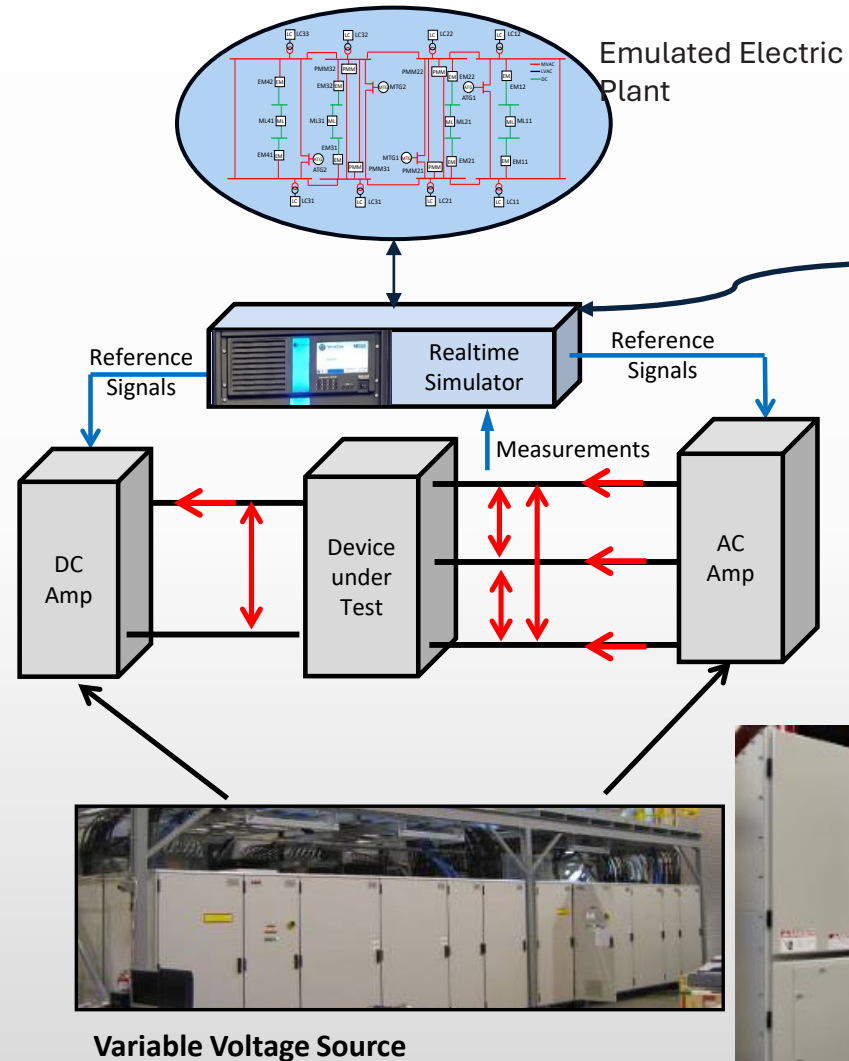
Power Hardware-in-the-Loop (PHIL) Simulation

Create a Virtual yet Realistic Environment to Rapidly Test and Demonstrate Equipment and Interfaces.

- Couple Device Under test (DUT) to a Real Time Computer Simulation using amplifiers and/or actuators, preserving natural coupling

Use of PHIL Simulation

- Testing in **Realistic** Environment
- **Early integration** testing
- Flexibility to **quickly change surrounding** system and conditions to test equipment performance envelope
- **Validate** System Specification & Interfaces
- Testing with **yet unrealized** system
- Test **extreme** conditions within controllable



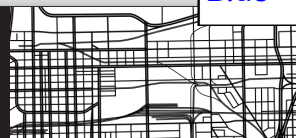
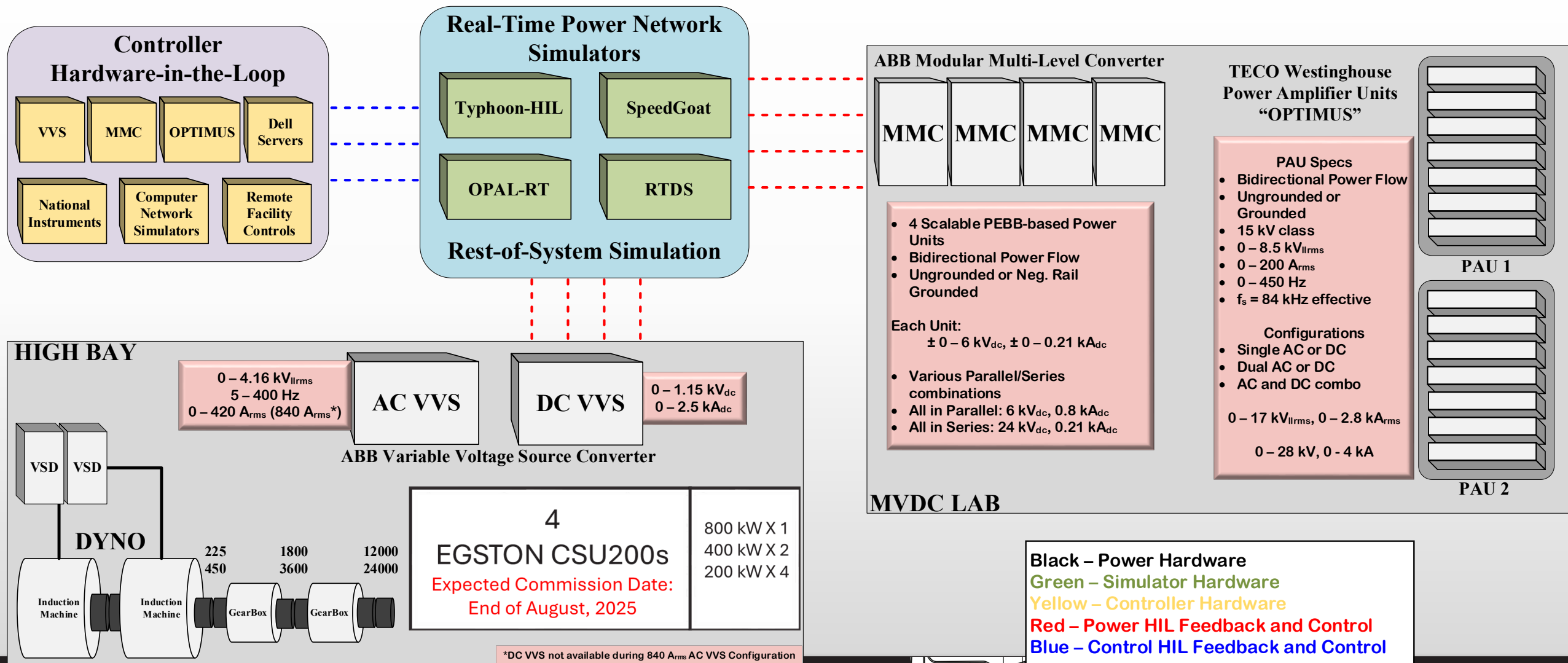
CAPS RT Simulators

- RTDS Novacore (9)
- SpeedGoat (2)
- Typhoon HIL (3)
- Opal-RT (2)

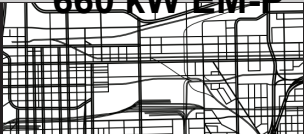
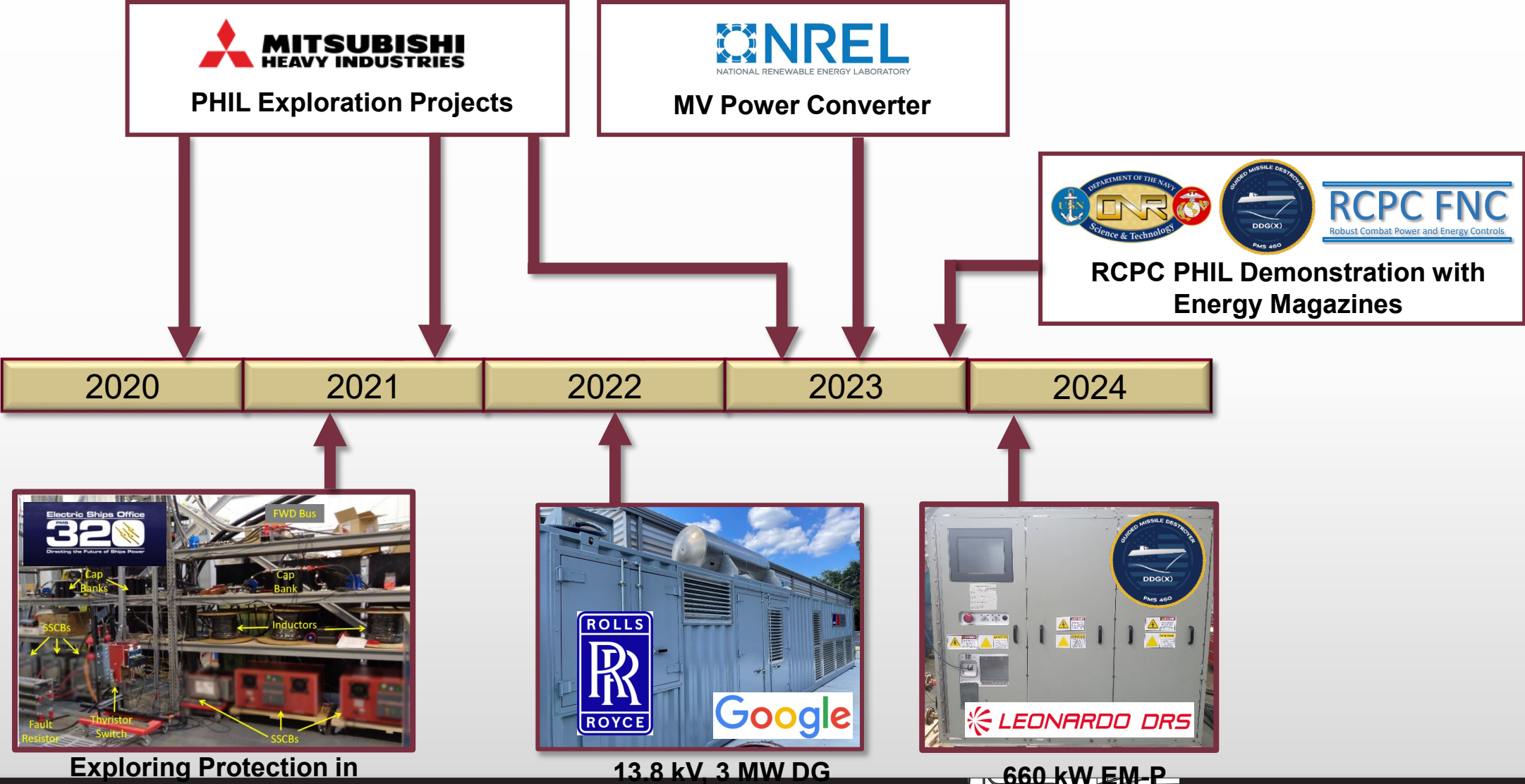




5 MW PHIL Facility Overview



Recent PHIL Testing Highlights at FSU-CAPS

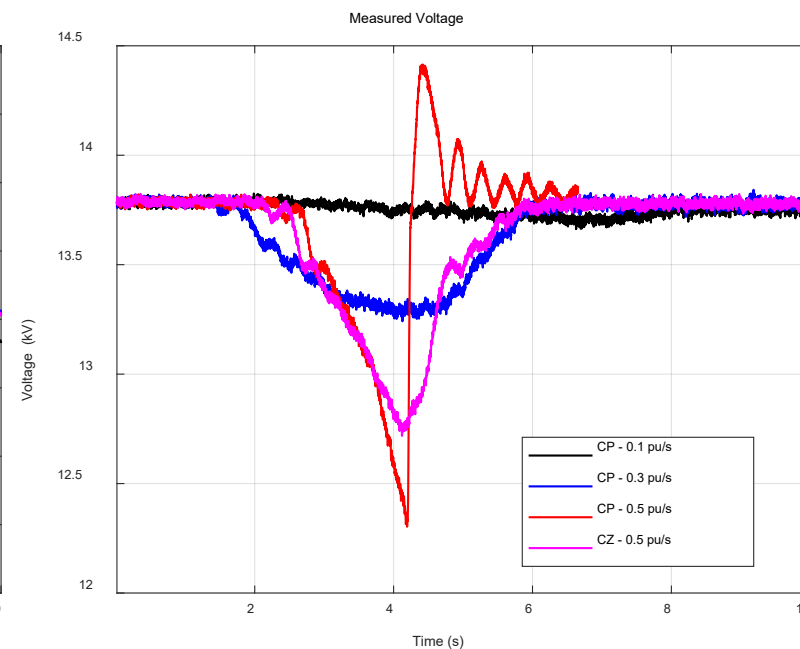
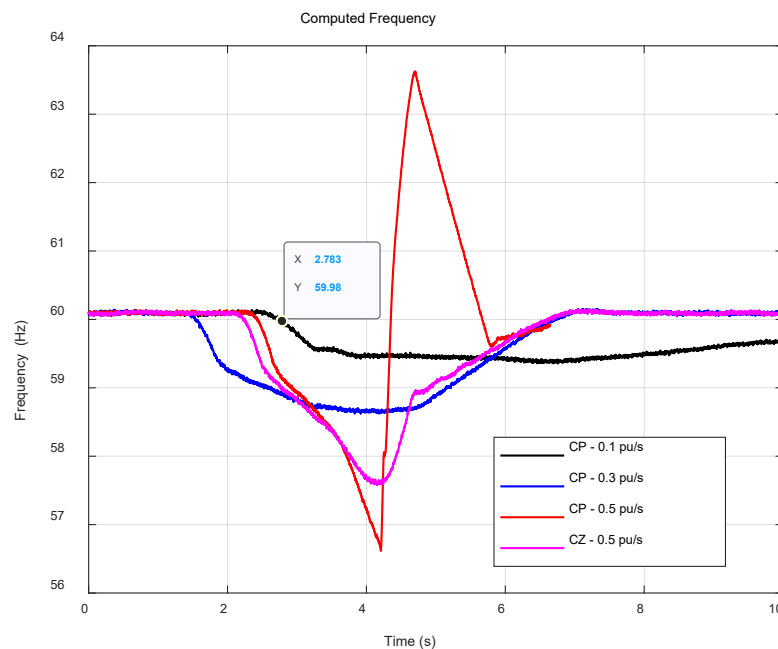
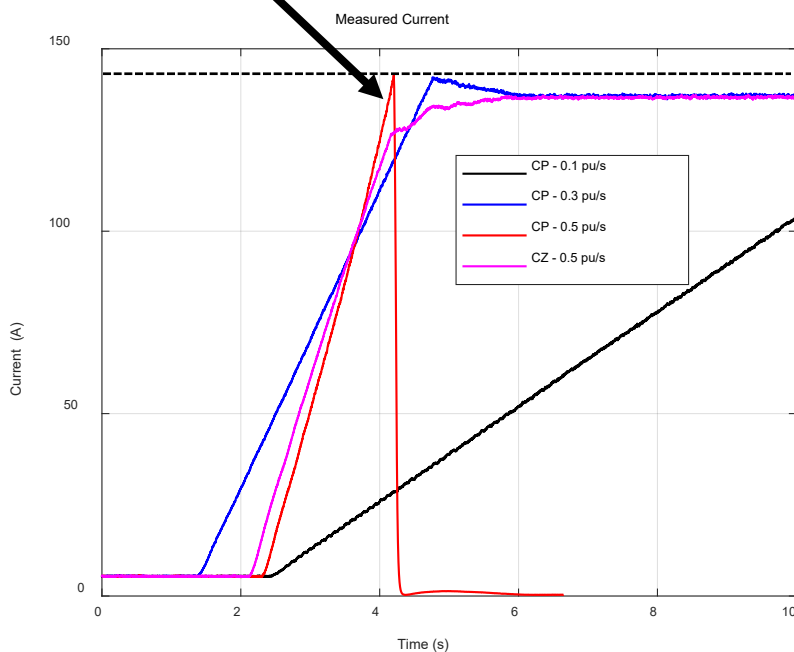


- # Testing
-
- 12.47 kV
- 4.16 kV
- 4.16 / 480 V
1.5 MVA
- LB
1-1.5 MW
 I_{aLB}, I_{bLB}
 V_{abLB}, b_{cLB}
- Amplifier references
- MMC
4x
0-6kV/208A
 $I_{m1}-I_{m4}$
 $V_{m1}-V_{m4}$
1 MW
LB
- VVS-DC/AC
50-1150 Vdc
2.5 MW
 I_{vvs}
 V_{vvs}
1-1.5 MW
LB
- EnableGates
- Optimus
0-13.8 kV
200 A
5 MW
0-450 Hz
 V_{fa}, V_{fb}
 V_{oa}, V_{ob}, V_{oc}
 I_{ga}, I_{gb}, I_{gc}
 V_{ga}, V_{gb}, V_{gc}
BrkStatus
BrkCmd
3
- DGC
DECS
G
3.0 MW / 3.16 MVA
0.95 PF, 60 Hz,
1800 rpm
Hardware of interest
- RTDS PHIL
HIL Controls
ROS
HIL Protection
IA
- ECU9 J1939
RPM
Tdem
Tact
CAN to UDP
- Ethernet (CAN messages)
- Fiber GTFPGA 8b/10b



Load Ramp Tests

RTDS detected overcurrent and gracefully stopped the experiment

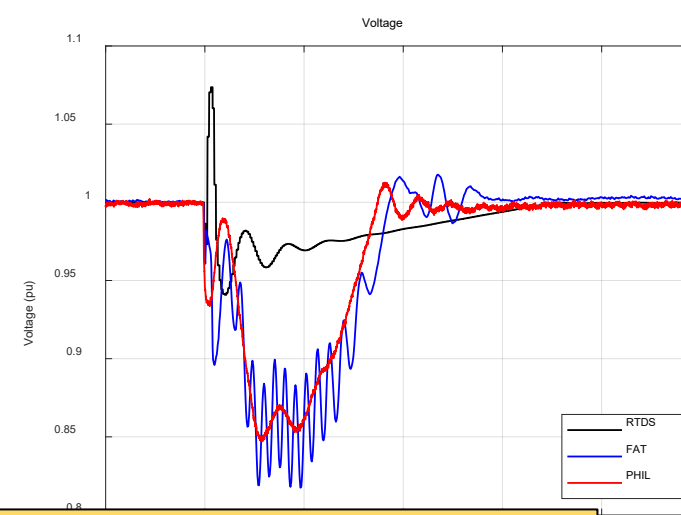
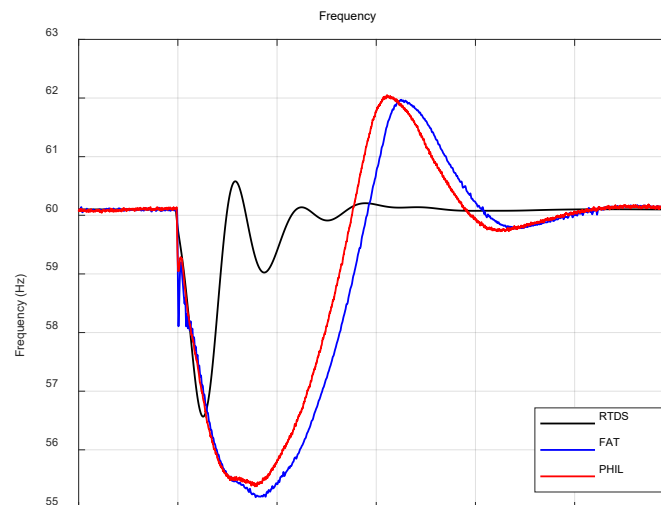
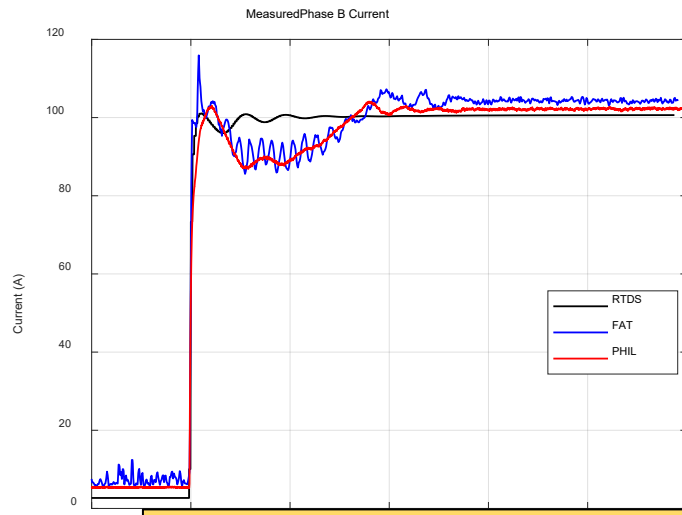


- Probing for limits: constant power load ramp rate of 0.5 pu/s caused by RTS based protection (current trip)
- Same setting feasible with constant impedance load

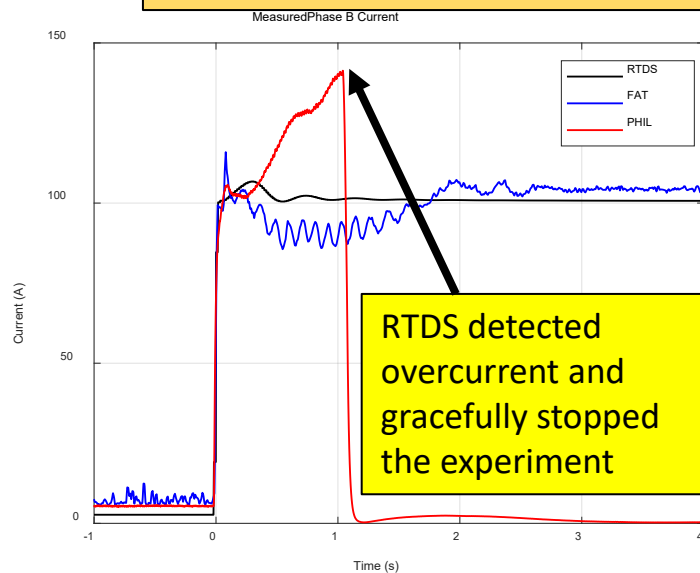


75% Block Load – Step Up

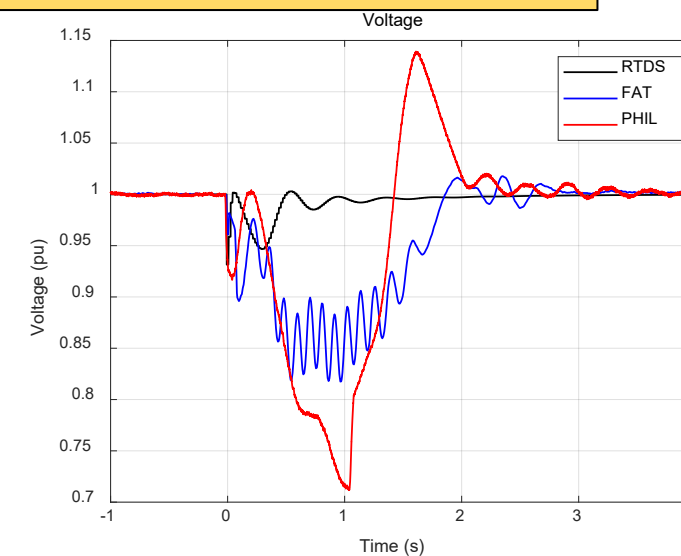
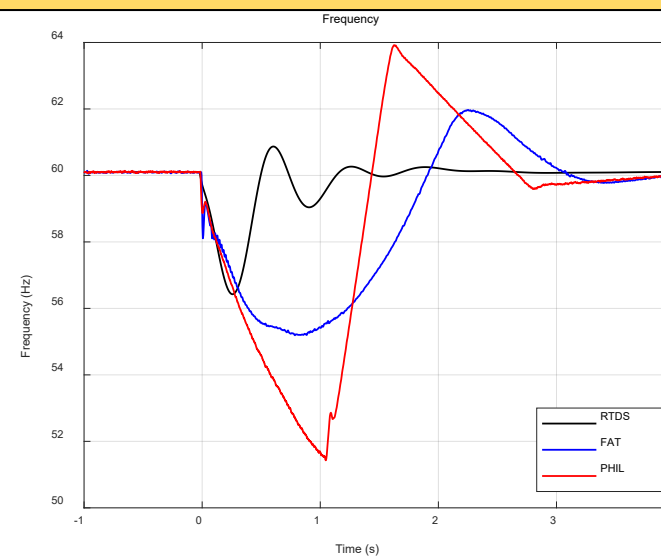
Constant Power vs FAT (Constant Impedance)



Top – Repeated FAT condition using PHIL – DG stable, bottom – Constant power type load presented to DG - unstable



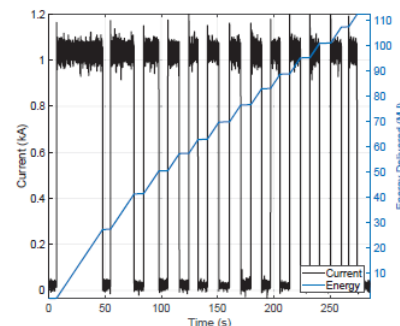
RTDS detected overcurrent and gracefully stopped the experiment



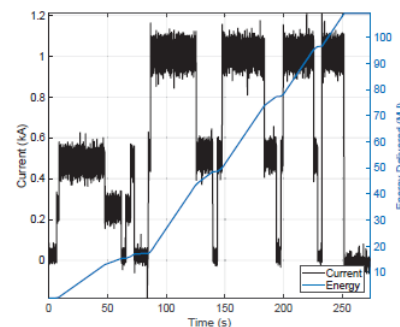
Load bank based testing inadequate to emulate data center loads

Testing 200 MJ Energy Magazine (EM) for Shipboard Systems

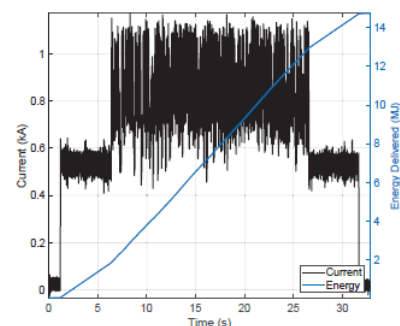
- DC PHIL Interface
 - Emulated pulsating mission loads and parallel PCM
 - DIM-IT IA
 - Used 2.5 MW, 1 kV DC amplifier
- AC PHIL Interface
 - Emulated generators and ship service loads
 - DQ-frame DIM-VT IA
 - Used 2.5 MW, 4.16 kV amplifier
- Studied voltage distortion, modulation, and disturbances in AC system
- Studied variety of DC load profiles (representing different types of loads)
- Gathered characterization data for modeling and model validation



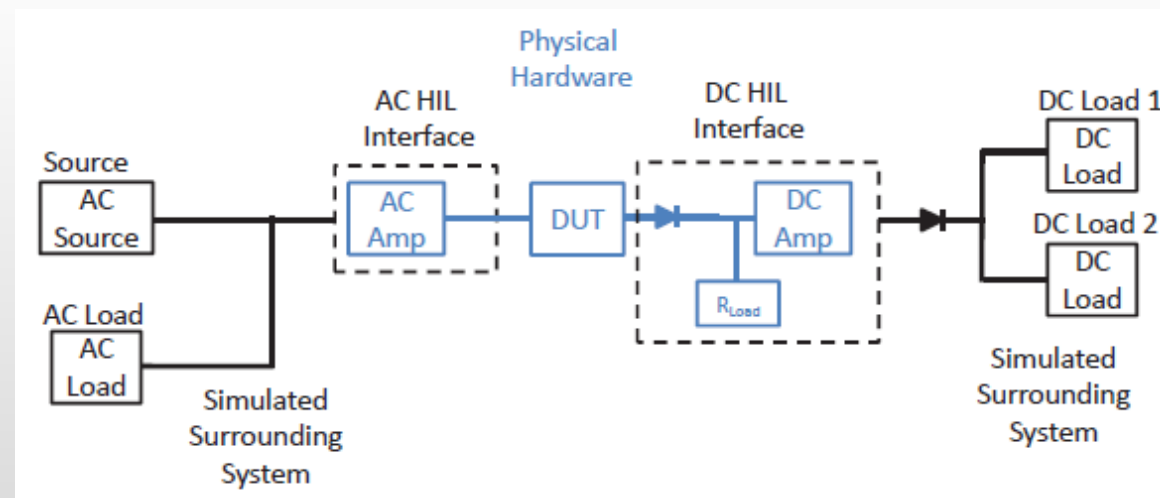
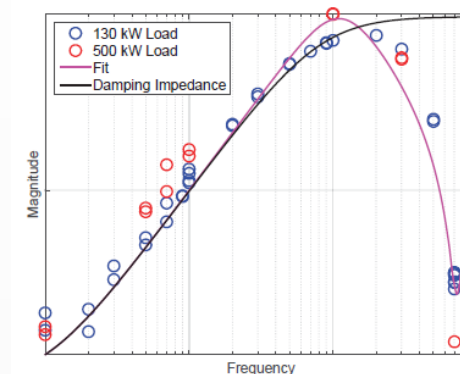
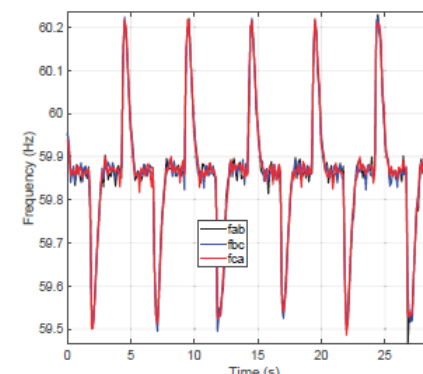
(a) Two-Level Periodic



(b) Multi-Level



(c) Base + Stochastic

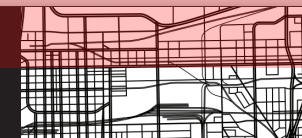
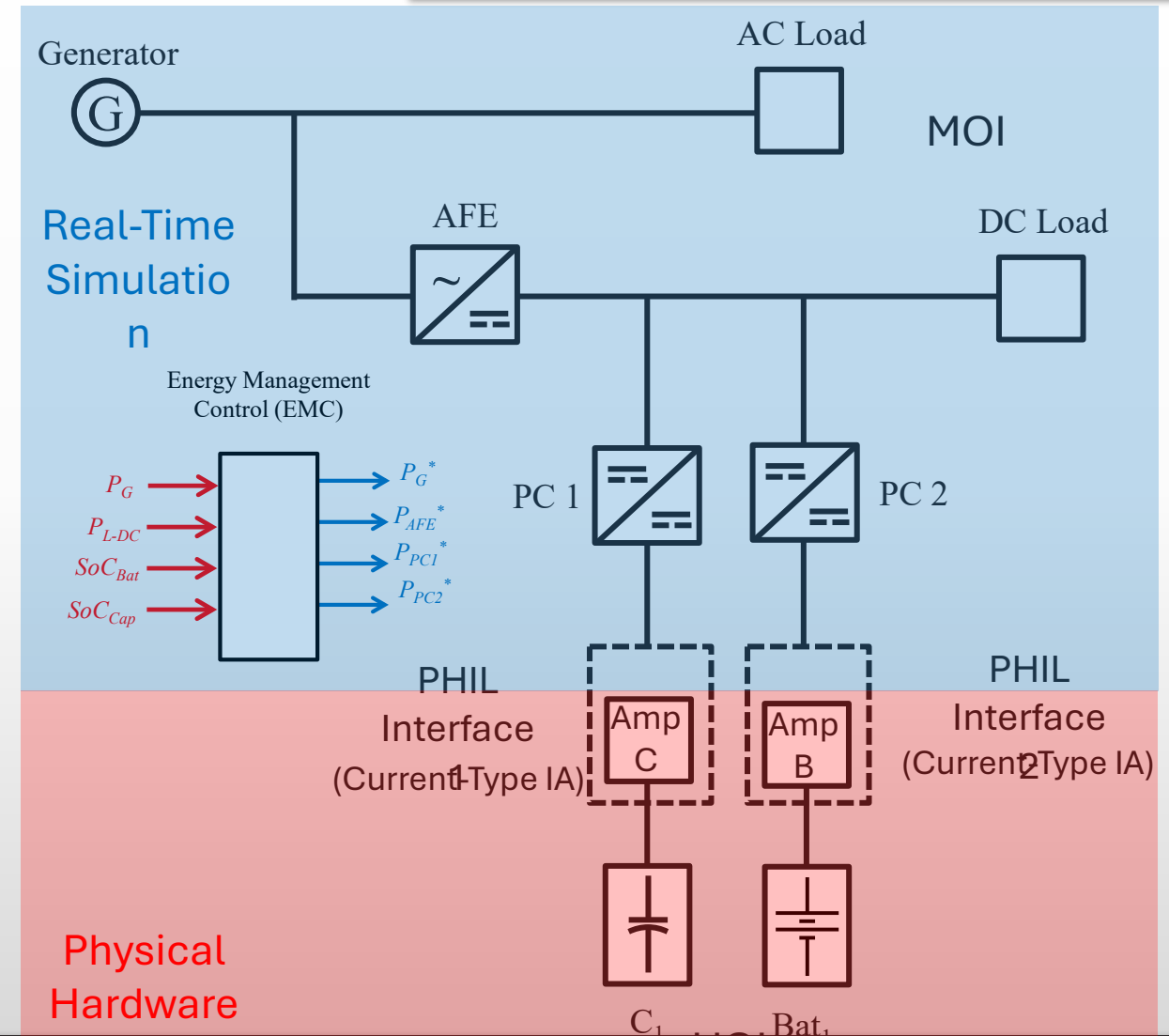


Testing of Energy Storage in Limited Inertia Systems



MITSUBISHI
HEAVY INDUSTRIES

- Model of Interest (MOI)
 - All components and controls, excluding the energy storage media
 - Executed on real-time simulator using 50 μ s time-step size
- Hardware of Interest (HOI)
 - Battery module
 - 45 Ah
 - Air cooled
 - 28 V nominal terminal voltage
 - Ultra-capacitor module
 - 53 F
 - Water-cooled
 - 170 V nominal voltage
- PHIL Interfaces



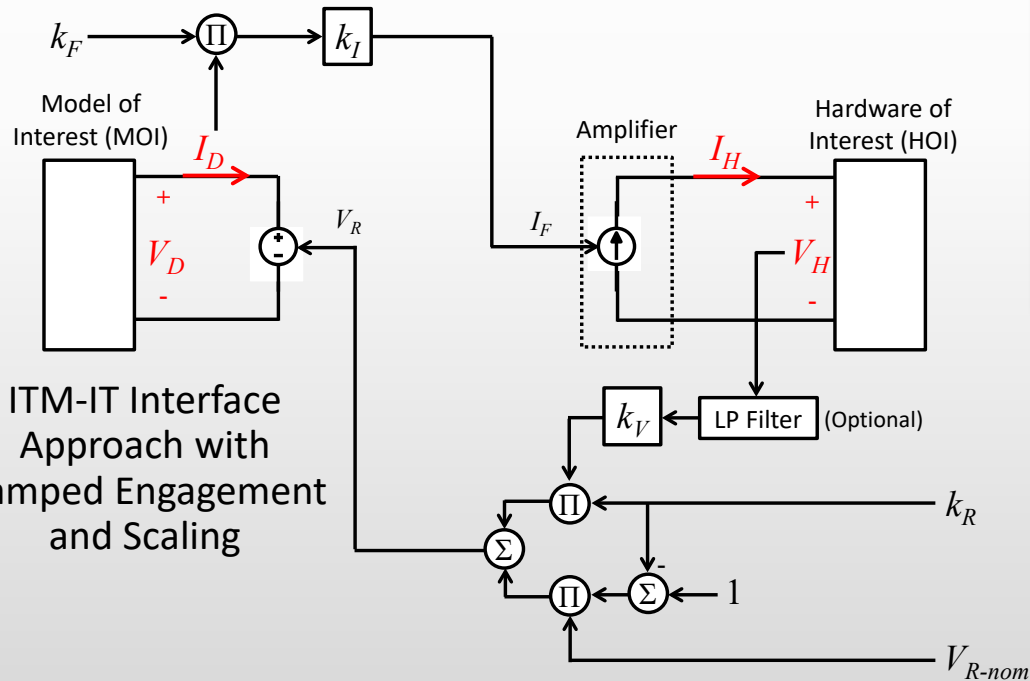
PHIL Interfaces

Current-type Ideal Transformer Model (ITM-IT) Interface Approach

- Gains for gradually engaging interface (k_F and k_R)
- Scale factors for scaling current and voltage across the interface (k_I and k_V)
- Low-pass filter on voltage feedback for stability and immunity to sensor noise (100 Hz cutoff frequency for battery interface)

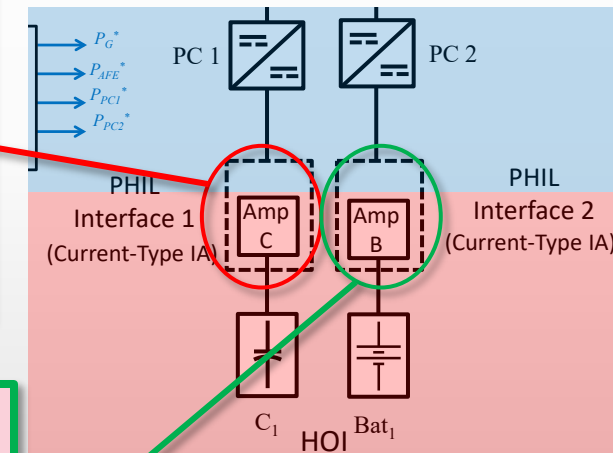
Amplifiers

- High bandwidth (> 5 kHz)
- 750 V, 100 kW
- Digital interface with RTS
- Operated multiple amplifier units in parallel for each PHIL interface



Interface to Capacitor Module

- 2 amplifier units in parallel (280 A)
- Single capacitor module scaled to represent 5s x 3p bank
 - $k_I = 1/3$
 - $k_V = 5$



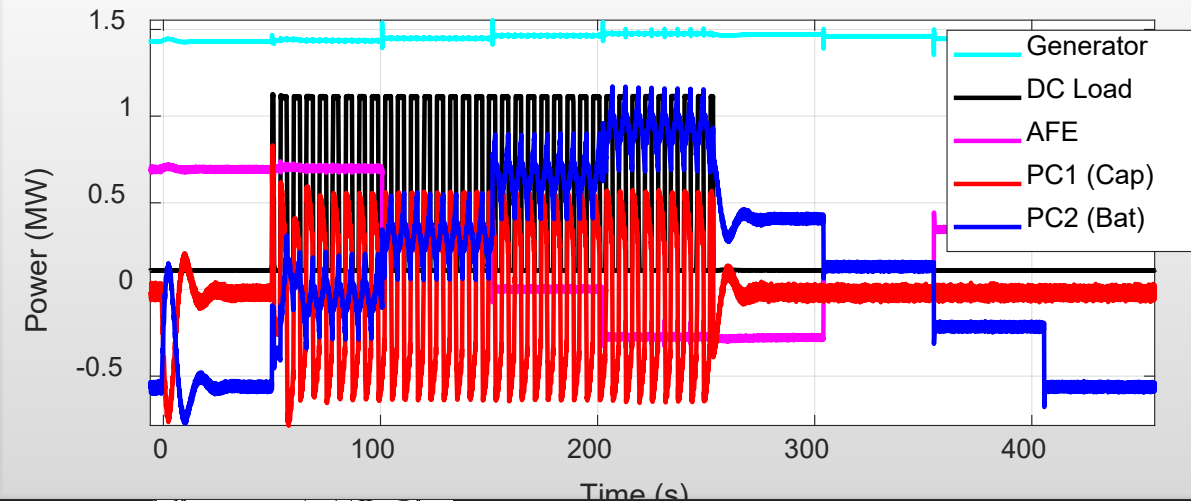
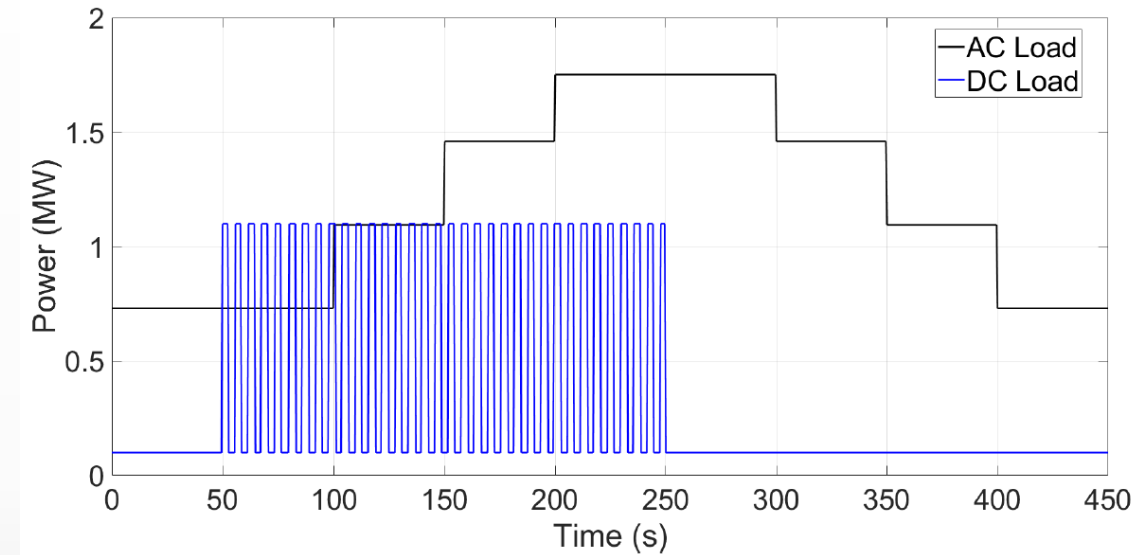
Interface to Battery Module

- 3 amplifier units in parallel (240 A*)
- Single battery module scaled to represent 28s x 7p bank
 - $k_I = 1/7$
 - $k_V = 28$

* Current limited by battery voltage, lower voltage limit of amplifiers, and voltage drop across series resistors used to facilitate current sharing between amplifiers

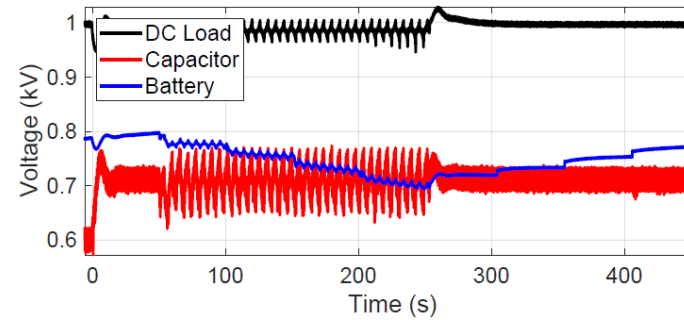
PHIL Simulation Experiments: Baseline Scenario

- Loading profile intended to test system in several modes of operation
- ($0 \text{ s} < t < 50 \text{ s}$) Base loading
- ($50 \text{ s} < t < 100 \text{ s}$) Pulse loading
 - Capacitor supplies load pulsations
- ($100 \text{ s} < t < 150 \text{ s}$) Battery supplements support of DC load
 - Total load exceeds generator capacity
- ($150 \text{ s} < t < 200 \text{ s}$) Battery fully supports DC load
 - AC load at generator capacity
- ($200 \text{ s} < t < 250 \text{ s}$) Battery supports DC load and supplements support of AC load
 - AC load at 120% of generator capacity
- ($250 \text{ s} < t < 300 \text{ s}$) Load pulsations cease
 - Battery supplied DC base load and supplements support of AC load
- ($300 \text{ s} < t < 350 \text{ s}$) Battery supports DC base load
- ($350 \text{ s} < t$) Battery recharges

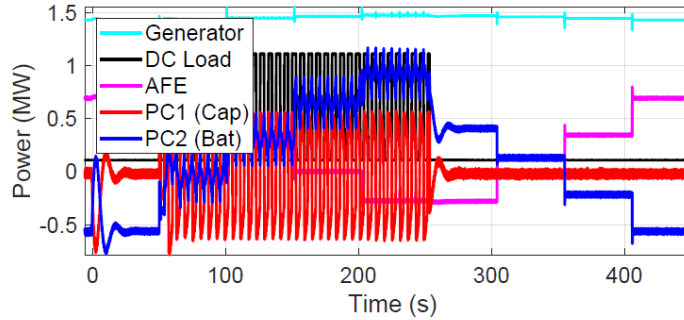


Results from PHIL Simulation Experiments

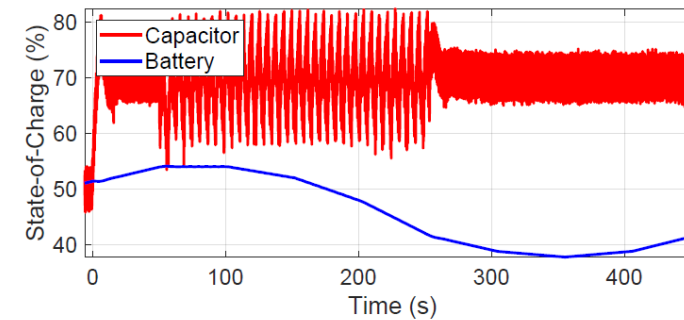
- Generator loading approximately held constant (near full load)
- Capacitor SoC generally maintained between 60% and 80%
- Voltage and current levels maintained within normal bounds



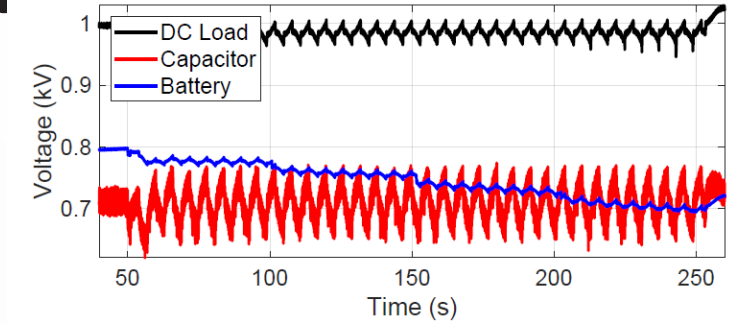
(a) Voltage



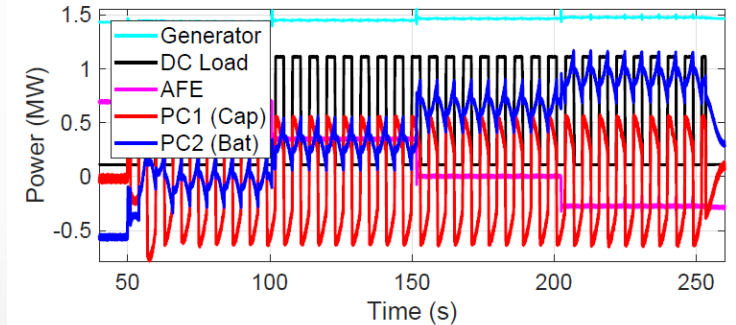
(b) Power



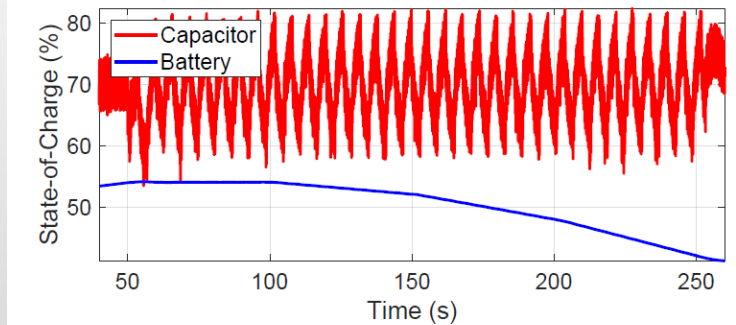
(c) State-of-Charge



(a) Voltage



(b) Power



(c) State-of-Charge

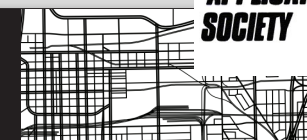
Thank You





Contributions: IEEE 2004-2025 Recommended Practice for Hardware-in-the-Loop Simulation

- **Michael “Mischa” Steurer** pioneered HIL and initiated IEEE WG P2004. Developed general linear formulation of PHIL experiment
- Collaboration: **PSRC WG CTF-33**; IEEE task force (TF) on “Real-Time Simulation of Power and Energy Systems”, chaired by Dr. Omar Faruque, under **IEEE WG 15.08.09** (within the General System Subcommittee of the IEEE PES T&D Committee)
- Sponsor: **PELS**, Co-sponsor: **IAS, IES**
- CAPS led one of the chapters (Execution of PHIL Experiments)
- CAPS members made substantial contributions to multiple chapters and annexes



High Speed Generator for Air Force Application

- Tested 2 MW high speed generator
- Used 5 MW dynamometers and high speed gearbox for 14,000 rpm interface
- Used high-speed diode rectifier at AC terminals of generator
- DC PHIL interface
 - ITM-IT IA
 - 2.5 MW, 1 kV DC amplifier
- Verified operation of the generator at full power
- Tested with constant-current ramp loading

Langston, J., et al. "Megawatt Scale Hardware-in-the-Loop Testing of a High Speed Generator." 2012 ASNE.

