

REAL TIME DIGITAL SIMULATION





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Real-Time Simulations Using a Synchrophasor-Based Wide Area Monitoring, Protection, and Control (WAMPAC) Testbed

A.C. Adewole R.Tzoneva

Centre for Substation Automation and Energy Management Systems (CSAEMS)

Cape Peninsula University of Technology



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- Background
- Objectives
- Methodology
- Experimental Results
- Conclusion
- Bibliography







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BACKGROUND

Power System Operations

- Provide reliable supply of electricity
- Efficient and secure operation

Current trend

- Large/complex interconnections
- Loads continue to increase
- Long distance between gens. & loads
- Lack of new power stations

Implications

- Power systems are stressed
- Systems are operating closer to their stability limit





BACKGROUND



Power System Stability



Figure 1: Power system stability (Kundur, 1994)





Voltage Stability Assessment (VSA)

Ability to maintain acceptable voltage profile during steady state conditions & after a disturbance

Causes of voltage instability:

- Small disturbances: Gradual increase in system loading
- Large disturbances: Loss of lines/generators, faults, transformer and generator controls (OLTCs/OXLs)
 - Lack of reactive power support
 - Loss of voltage control

Analysis:

- The proximity of the system to voltage collapse
- Mechanism of voltage collapse (how?, why?, what, where the voltage weak areas are? effectives RAS.



BACKGROUND



System Integrity Protection Schemes for VSA (RAS, SPS, SIPS)

Functions

- Monitor
- Detect abnormal system conditions
- Initiate remedial action(s)
- Preserve system integrity

SIPS Elements

- System monitoring element
- System protection element
- Execution element





System Integrity Protection Schemes for VSA (RAS, SPS, SIPS)

Table 1: Remedial actions for power system instability

SIPS/RAS/SPS	Transient instability	Small-signal instability	Frequency instability	Voltage instability	
Generation rejection	×	×	×	×	
Remote load shedding	×	×			
HVDC controls	×	×	×		
Braking resistor	×	×			
Under-frequency load			×		
shedding					
Turbine fast valving	×	×	×		
Automatic shunt switching	×	×		×	
Under-voltage load				×	
shedding					
Tap-changer blocking			×	×	
AGC controls		×		×	
Gas turbine start-up			×	×	





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OBJECTIVES

Proposed algorithms and methods for WAMPAC









Features

- 1µs synchronization to the GPS,
- Reporting rates up to 200 fps for 50 Hz systems
- Accuracy of 1% TVE
- Compliance with IEEE C37.118 Std.



OBJECTIVES



Phasor format

Time

Phase

GPS

Timestamp

Magnitude

Applications of synchrophasors

- Situational awareness
- Wide area monitoring systems
- Linear state estimation,
- Decision support
- Real-time analysis
- Protection and control
- Model validation





OBJECTIVES



Table 2: Comparison with existing technology

Existing Technology	Emerging Technology
SCADA Data	Phasor Measurement -PMU
Refresh rate = 2-10 seconds	Refresh rate = 200 samples per second (50 Hz)
Magnitude only	Magnitude & phase angle
Measurements are not time synchronized	Measurements are time synchronized
Legacy communication technology	Modern communication technology
Not suitable for rapidly changing system conditions	Suitable for capturing dynamic changes
X-ray	MRI





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- Derivations of real-time voltage stability indices
 Generator reactive power reserve
- Derivation for centralized SIPS (undervoltage load shedding scheme)
 - MVAR mismatch, Voltage Control Areas (VCA), volt deviation
- Development of a 'proof-of-concept' testbed
- Modelling of the test systemNew England 39-bus test system
- Real-time hardware-in-the-loop simulations of case studies
 - Case studies: Load increase, generator contingencies, line contingencies



Proposed Real-Time Voltage Stability Indices (RVSA) indices

Derivation from generator maximum reactive power reserve

$$Q_{g \max} = -\frac{V_g^2}{X_s} + \sqrt{\frac{V_g^2 I_{fd \max}^2}{X_s^2} - P_{g \max}^2} \qquad RVSA_{Q,i} = \left(1 - \frac{Q_{gki}}{Q_{g \max i}^c}\right) \times 100\%$$
(1)

Generator field current derivation from Q_{g max}

$$-\frac{V_g^2}{X_s} + \sqrt{\frac{V_g^2 I_{fd\,\max}^2}{X_s^2} - P_{g\,\max}^2} = -\frac{V_g^2}{X_s} + \sqrt{\frac{V_g^2 I_{fdk}^2}{X_s^2} - P_{gk}^2} \quad RVSA_{Ifd,i} = \left(1 - \frac{I_{fdki}}{I_{fd\,\max\,i}}\right) \times 100\%$$
(2)

Generator stator current derivation $Q_{ga\max} = \sqrt{V_g^2 I_{a\max}^2 - P_{ga\max}^2} \qquad RVSA_{Ia,i} = \left(1 - \frac{I_{aki}}{I_{a\max i}^c}\right) \times 100\% \qquad (3)$



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Proposed RVSA indices for large interconnected power system

Reactive power reserve on system generators

$$RVSA_{Q,sys} = \min_{i \in sys} \left\{ RVSA_{Q,i} \right\} = \min_{i \in sys} \left\{ \left(1 - \frac{Q_{gki}}{Q_{g\max i}^c} \right) \times 100\% \right\}$$
(4)

Field current reserves on system generators

$$RVSA_{Ifd,sys} = \min_{i \in sys} \left\{ RVSA_{Ifd,i} \right\} = \min_{i \in sys} \left\{ \left(1 - \frac{I_{fdki}}{I_{fd\max i}^c} \right) \times 100 \% \right\}$$
(5)

Stator current reserves on system generators

$$RVSA_{Ia,sys} = \min_{i \in sys} \left\{ RVSA_{Ia,i} \right\} = \min_{i \in sys} \left\{ \left(1 - \frac{I_{aki}}{I_{a \max i}^{c}} \right) \times 100\% \right\}$$
(6)



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Derivations for undervoltage load shedding scheme

Total reactive power mismatch

$$\Delta Q_{gik} = Q_{gik} - Q_{gi0}, \quad i = \overline{1, N_g}, \quad k = 0, 1, 2, \dots$$
 (7)

Total load to shed

$$Q_{shed,k} = \beta_K \cdot \sum_{i=1}^{N_g} \Delta Q_{gik}, \ k = 0, 1, 2, ...$$
 (8)

Total load to shed per VCA

$$\Delta Q_{shed,VCA_{jk}} = \left(\frac{100 - vcaRVSA_{jk}}{100n - \left(\sum_{j=1}^{n} vcaRVSA_{jk}\right)}\right) \times Q_{shed,k} \qquad j = \overline{1,n}, \quad k = 0, 1, 2, \dots$$
(9)

• Total load to shed per VCA per load bus $\Delta Q_{shed, jBp} = W_{j\Delta VBp} \times \Delta Q_{shed, VCAjk}$



(10)

SIPS elements for undervoltage load shedding



Figure 3: System Integrity Protection Scheme (SIPS)



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Testbed used at CSAEMS-CPUT

RTDS, PMUs, PDCs, IEDs, GPS Clocks, PLC, Network Switches



Figure 4: Implemented WAMPAC testbed

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Table 3: RTDS Resources at CPUT (4 Racks)

S/N	RTDS Card	Function	Nr.
1	PB5	Processor card	6
2	GPC	Processor card	3
3	GTWIF	Work station interface	4
4	GTNET	Communication protocols (PMU, GSE, SV, DNP3)	5
5	GTNET X2	Communication protocol X2 (GSE, SKT)	1
6	GYSYNC	Time synchronization	2
7	GTAO	Analogue output card	2
8	GTAI	Analogue input card	1



Test System Model





_rtds_GTNET_PMU_v5.def										
PMU13 CC	DNFIG PM	U14 CONFIG	PMU15 CC	NFIG	PMU16 C	ON	FIG			
PMU9 C	ONFIG	PMU10 CON	PMU1	1 CONFIG			PMU12 CONFIG			
PMU5 (CONFIG	PMU6 COI	VFIG	PMU7	7 CONFIG		P	MU8 CO	NFIG	
CONFIGU	RATION	PMU1 CONFIG	PMU2 C	ONFIG	PMU3 (CON	FIG	PMU4 0	CONFIG	;
Name		Descriptio	n		Value		Unit	Min	Max	
eC37data	Enable output	t of C37.118 data u	using GTNET		Yes	-		0	1	
Name	GTNET Comp	oonent Name			PMUCharli	е				
pmutype	PMU Model Ty	ype			Annex	-		0	0	
cfgtype	Configuration	frame format			Config 2	-		0	1	
freq	Base Frequer	ncy (Hz)			60.0	-		0	1	
nPMU	Number of PM	IUs (maximum 24	-)		16	-		0	34	
adv	Delay Input Si	ignal to align V & I			V bv 1dt	-		0	1	
eAngM	Enable Angle	Difference Meter			NO	-		0	1	
nAngDiff	Angle Differen	nce Meter Name (F	PMUx-PMUy)		angdiff			0	0	
sfx	Plot Signal Su	uffix								
calib_const	Common cali	bration offset appl	ied to all PMU	inputs	0	d	egrees	-360.0	360.0	
dt_adj	Time-step adj	justment to all inp	ut signals		-3	d	t	-500	500	
ePri	Enable Prima	ry Signals			YES	-		0	1	
GT_SOC	GTSYNC adva	ance TIME signal r	name		ADVSECD			0	0	
GT_STAT	GTSYNC adva	ance STAT signal i	name		ADVSTAT			0	0	
phs_rot	Phase Rotation	on			ABC	-		0	1	
Port	GTIO Fiber Po	ort Number			1			1	8.	
Card	GTNET_PMU		1			1	8			
Proc	Assigned Cor	ntrols Processor			3			1	40	
Pri		1			1		-			
		Update	Cancel	C	ancel All					

<u>PMU</u> RSCAD Draft GTNET-PMU Component



Figure 7: RSCAD-PMU component

PMU Parameters:

- IEEE C37.118.1-2011
- P-Class
- Positive sequence phasors $V_1 \& I_1$
- Analogue measurement and digital word
- Polar format, real values, 60 fps, CFG-2
- IRIG-B time sync from the GTSYNC card



GTNET-PMU Card



RSCAD Runtime

🛓 Run	NTIME 4.004											
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A			GPS	Time							 A 1 	rack0
	YEAR	MONTH	DAY	HOUR	MINUTE	SECOND					Cape Peninsula	rack1
_	2016	1		10	53	29					University of Technology	
				(GENERATORS ME	TERING PALETTE				С		rack4
닅	P40	P2	P3	P4	P5	P6	P7	P8	P9	P1		
	996.6	553.2	667.2	629.5	508.2	676.6	569.4	540.1	810.8	246.7		
0	040	02	03	04	05	06	07	08	09	01	Loadoff Loadoff Loadoff CBOPE CBCLS1 CBOPE	
>	279.0	230.7	279.1	154.0	166.8	236.0	110.2	55.32	57.08	185.6		
· · · ·	VGB40	VGB2	VGB3	VGB4	VGB5	VGB6	VGB7	VGB8	VGB9	VGB1		
**	0.9882	0.956	0.9727	0.9956	1.005	1.045	1.055	1.024	1.025	1.038		
~~	If40	162	lf3	IfA	165	Iff	157	If8	IfQ	If1	GEN6GEN7	
⊣⊢	2.415	2.394	2.413	2.176	4.013	2.314	2.104	1.939	2.029	1.719		
100												
1015	EF40	EF2	EF3	EF4	EF5	EF6	EF7	EF8	EF9	EF1		
1	2.417			<u>j 2.187</u>	4.013	<u>J</u> 2.320	<u></u>	1.944	2.031	1.720		
1	W40	W2	W3	W4	W5	W6	W7	W8	W9	W1		
Λ.	377.0	377.0	377.1	377.0	377.0	377.0	377.0	377.0	377.0	377.0	(P,BUS33:1) UVLS CTRL	
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	43.82	26.24	31.12	27.24	22.27	28.70	23.01	22.19	33.19	12.44	0.55 0.72 LD#FOR LD#FOR LD19FO. LD19FD. LD19FD. LD19FD. LD19FD. LD19FD. LD19FD.	
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WARNI	NG - the desi //ATIONAL: R	criptor vector un Started S	r is null for a Successfully	component L	.ockFree. Di	sabling the	component					^

Figure 9: Runtime module with meters and controls



RSCAD Runtime



PMU vector plots

Figure 10: Runtime module with meters and PMU vector plots





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Simulation: Dynamic Analyses using the RTDS

Combinations of small disturbances & large disturbances **Case Studies:**

- Case Study 1: Increased system loading
- Case Study 2: *N*-2 line contingencies + load increase
- Case Study 3: *N*-2 generator contingencies + load increase
- Case Study 4: Load increase + transformer ULTC & Generator OXL dynamics

				rtds_sharc_ctl_SC	HED		
Dynamic Load	+2 +3 2	CONFIGUE	RATION SCHEDULE (1-10)			
Scheduling		Name	Description	Value	Unit	Min Max	
Scheduning		note	Note: T1 <t2<t3< td=""><td></td><td></td><td></td><td>-</td></t2<t3<>				-
	RISC	T1	If time >=	1.0	0.0	1e6	
	Load8	Y1	Output=	1065.75	-1e3	38 1e38	
	Tour not	T2	If time >=	2.0	0.0	1e6	
ſ	S Set	Y2	Output=	1119.04	-1e3	38 1e38	
		T3	If time >=	3.0	0.0	1e6	
		Y3	Output=	1174.99	-1e3	38 1e38	
		T4	If time >=	4.0	0.0	1e6	
		¥4	Output=	1233.74	-1e3	38 1e38	
	0	T5	If time >=	5.0	0.0	1e6	
		Y5	Output=	1295.43	-1e3	38 1e38	
		T6	If time >=	6.0	0.0	1e6	
	. о <u>т</u> .	Y6	Output=	1360.20	-1e3	38 1e38	
	T 11 II I		Upda	te Cancel	Cancel All		

Testing with PMU Connection Tester

PMU Connection Tester
File Help
Connection Parameters
Icp Udp Serial File Default System IP Stack: IPv6 Protocol
Host IP: 192.168. 1.203 Port: 4710 Network Interface Hestablish Tcp Server Network Interface IEEE C37.118.2-2011 Device ID Code: 10 Command: Disable Realtime Data Send
PMU: ID Code: 10
INC. INC. <td< td=""></td<>
Frame Type: DataFrame Time: 2016-01-21 11:23:57:933 Frequency: 59:9654 Hz Angle: -117.427617494094* Magnitude: 7.7167 (13.3657) kV
Uisplay: Hexadecimal

Figure 12: PMU connection testing



Testing with RTDS PMU Utility



Figure 12: PMU connection testing

University of Technology

Ethernet Capture using Wireshark Network analyzer

RTDS_Synchrophasor_Wireshark.pcapng [Wireshark 1.8.1	(SVN Rev 43946 from /t	runk-1.8)]	and in case of the local diversion of the loc		- • ×			
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No. Time Source	Destination	Protocol Le	ength Info		A			
2385 11.693849000 192.168.1.33 2408 12 693284000 192 168 1 33	192.168.1.203	SYNCHRC	72 Command Frame	, data transm	frame			
2410 12.942782000 192.168.1.203	192.168.1.33	SYNCHRC	488 Configuration	Frame 2	TT diffe			
2411 12.946393000 192.168.1.33	192.168.1.203	SYNCHRC	72 Command Frame	, data transm	nission on			
2424 14.441348000 192.168.1.203	192.168.1.33	SYNCHRC	114 Data Frame					
2430 14.481333000 192.168.1.203	192.168.1.33	SYNCHRC	114 Data Frame					
2432 14.501305000 192.168.1.203	192.168.1.33	SYNCHRC	114 Data Frame					
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······································		evened (012 bd						
Ethernet II Src: RtdsTech 05:92 (00:50), 114 bytes cap .c2.4f.95.92) n	tured (912 D1 st: Compalin	59:e8:6f (1c:75:08	·59.e8.6f)	A			
Internet Protocol Version 4, Src: 192.1	68.1.203 (192.16	8.1.203), Dst	: 192.168.1.33 (19)	2.168.1.33)				
	: 4710 (4710), D	st Port: btpr	jctrl (2803), Seq:	4275, Ack: 5	55, Len: 60			
□ IEEE C37.118 Synchrophasor Protocol, Da	ta Frame							
Synchronization word: 0xaa01 Framosizo: 60								
PMU/DC TD number: 10								
SOC time stamp (UTC): 2016-01-21 11:12	8:50							
Time quality flags					=			
Fraction of second (raw): 50000								
Measurement data, using frame number .	2410 as configur	ation trame						
I Flags								
Phasors (2)								
Phasor #1: "PHASOR CH 1:V1 ",	7452.73V/11	3.48°						
Phasor #2: "PHASOR CH 2:I1 ",	47999.03A/12	4.93°						
Rate of change of frequency: -0.0	nz 67328Hz/s							
Analog values (4)	57 520112/5							
Digital status words (1)					-			
•					•			
0000 1c 75 08 59 e8 6f 00 50 c2 4f 95 92	08 00 45 00	.u.Y.o.P .O	E.					
0010 00 64 21 70 40 00 40 06 94 da CO a8 0020 01 21 12 66 0a f3 be ff a4 98 e1 a6	5 01 CD CO a8 . 5 41 98 50 18 .	.ɑ!}@.@	A. P.		E			
0030 40 00 19 7b 00 00 aa 01 00 3c 00 0a	56 a0 be 9a 🤇	a{	·					
0040 00 00 C3 50 00 00 45 e8 e5 df bf fc	1 83 C1 4/ 3D .	PE			-			
Figure 13: Synchrophasor packet snifting using Wireshark								

Aggregation using the SEL-5070 PDC

Unnamed Connection - PDC Assistant

SEL Open Save Save As Close Send Settings Connect Disconnect Local Services Home **Real-time Status** Settings Input Connections Inputs Name PDC ID Connection State Time Quality Received Data Frames Outputs - SVP 6554 Receiving Data Normal 598 Input PMUs Calculations PMU Name PMU ID Input Connection PMU State PMU Status Unlock Time Archives SVP 6554 SVP OK Found Locked Loggers Timestamp 01/21/2016 11:44:44.416 Frequency 60.015 Hz. df/dt -0.038 Hz./s Globals Phasors Analogs Digitals = Nominal Status Name Magnitude Angle Name Value DWO[001]-BIT01 DWO[001]-BIT02 DWO[001]-BIT03 DWO[0011-BIT04 PO V[001] 7774.420 -74.470 AOI0011 290.884 Real-time PO V[002] 7488.820 -77.230 AO[002] 241.116 **Diagnostic Logs** DWO[001]-BIT08 DWO[001]-BIT05 DWO[0011-BIT06 DWO[001]-BIT07 PO V[003] 7561.377 AO[003] 258.174 -75.258 PO_V[004] 7944.549 -75.675 AO[004] 177.691 Data PO_V[005] 0.000 0.000 AO[005] 174.554 DWO[001]-BIT09 DWO[001]-BIT10 DWO[001]-BIT11 DWO[001]-BIT12 Retrieve Archives PO_V[006] 8013.952 -77.049 AO[006] 257.544 n Administration PO_V[007] 8335.417 -73.595 AO[007] 120.351 PO V[008] 8409.119 AO[008] 64.774 DWO[001]-BIT13 DWO[001]-BIT14 DWO[001]-BIT15 DWO[001]-BIT16 -70.795 Device -74.724 AO[009] 68.479 PO V[009] 8139.944 0 PO_V[010] 8080.924 -71.749 AO[010] 201.925 User Accounts DWO[002]-BIT01 DWO[002]-BIT02 DWO[002]-BIT03 DWO[002]-BIT04 PO_I[001] 45748.457 -89.201 AO[011] 2.469 General Security PO_I[002] 27041.595 -99.531 AO[012] 2.454 PO_I[003] 30669.145 -95.954 AO[013] 2.369 DWO[002]-BIT05 DWO[002]-BIT06 DWO[002]-BIT07 DWO[002]-BIT08 I DAP PO_I[004] 27506.444 -90.425 AO[014] 2.216 0 0 0 PO I[005] 0.000 0.000 AO[015] 4.012 DWO[002]-BIT10 DWO[0021-BIT09 DWO[002]-BIT11 DWO[002]-BIT12 PO_I[006] 22218.636 -94.992 AO[016] 2.301 0 0 0 0 PO_I[007] 27908.031 -94.202 AO[017] 2.098 AO[018] 1.954 PO_I[008] 22646.123 -81.839 DWO[002]-BIT13 DWO[002]-BIT14 DWO[002]-BIT15 DWO[002]-BIT16 PO I[009] 22153.250 -80.613 AO[019] 2.075 0 0 0 0 PO_I[010] 34189.497 -75.382 AO[020] 1.762 AO[021] 45246.840 AO[022] 27256.590 AO[023] 30861.220 AO[024] 27475.210 AO[025] 22176.340 Project Status - No Errors PDC Sync - Synchronized PDC Connectio Figure 14: Aggregation of PMU measurements using the PDC

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Case Study 1



generator MVAr for increased system loading



Case Study 2



Figure 16: Case Study 2: : Real-time plots of voltage phasors and generator MVAr for *N-2* Line contingency and increased system loading



Case Study 3



Figure 17: Case Study 3: Real-time plots of generator-derived indices for increased loading conditions, line - generator contingencies, and OXL operation









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- Three generator-derived RVSA indices based on PMU measurements
- Comparison of the various RVSA indices.
 - EGSCR index gave the best performance
 - Less sensors, less measurements,
 - ease of practical implementation
- SIPS using undervoltage load shedding
- A real-time 'proof-of-concept' testbed was implemented
- Future work: Impact of pervasive network conditions and cyber security in wide area applications





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Thank you

Questions?

